NETLOGO CODE

set perceived-hardship random-float 1.0

set active? false set jail-term 0 display-agent

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;; SOCIAL MEDIA IN UK RIOTS
;; Original model by Uri Wilensky, modified by Antonio A. Casilli and Paola Tubaro on 10 August 2011.
;; Authorised by copyright notice as reported below.
;; Original model available in the Netlogo model library, downloadable at: http://ccl.northwestern.edu/netlogo/
breed [agents agent]
breed [cops cop]
globals [
              ; factor for determining arrest probability
 k
 threshold
                 ; by how much must G > N to make someone rebel?
agents-own [
                  ; R, fixed for the agent's lifetime, ranging from 0-1 (inclusive)
 risk-aversion
 perceived-hardship; H, also ranging from 0-1 (inclusive)
 active?
                ; if true, then the agent is actively rebelling
jail-term
                ; how many turns in jail remain? (if 0, the agent is not in jail)
patches-own [
 neighborhood
                   ; surrounding patches within the vision radius
to setup
 clear-all
 ;; set globals
 set k 2.3
 set threshold 0.1
 ask patches [
  ;; make background a slightly dark gray
  set pcolor gray - 1
  ;; cache patch neighborhoods
  set neighborhood patches in-radius vision
 ;; create cops
 create-cops round (initial-cop-density * .01 * count patches) [
  move-to one-of patches with [not any? turtles-here]
  display-cop
 ;; create agents
 create-agents round (initial-agent-density * .01 * count patches) [
  move-to one-of patches with [not any? turtles-here]
  set heading 0
  set risk-aversion random-float 1.0
```

```
;; plot initial state of system
 update-plots
end
to go
 ask turtles [
  ; Rule M: Move to a random site within your vision
  if (breed = agents and jail-term = 0) or breed = cops
   [ move ]
  ; Rule A: Determine if each agent should be active or quiet
  if breed = agents and jail-term = 0 [ determine-behavior ]
  ; Rule C: Cops arrest a random active agent within their radius
  if breed = cops [ enforce ]
 ; Jailed agents get their term reduced at the end of each clock tick
 ask agents
  [ if jail-term > 0 [ set jail-term jail-term - 1 ] ]
 ; update agent display
 ask agents [display-agent]
 ask cops [ display-cop ]
 ; advance clock and update plots
 tick
 update-plots
 if ticks = 1000 [stop]
;; AGENT AND COP BEHAVIOR
;; This was the original model by U. Wilensky (now inactive)
;; move to an empty patch
;;to move ;; turtle procedure
 ;;if movement? or (breed = cops) [
   ;; move to a patch in vision; candidate patches are
   ;; empty or contain only jailed agents
 ;; let targets neighborhood with
            [not any? cops-here and all? agents-here [jail-term > 0]]
   if any? targets [ move-to one-of targets ]
;; ]
;; end
;; These are the modifications introduced by A. Casilli and P. Tubaro on 10 August 2011
to move ;; turtle procedure
 ;; for cops only: it is just the same as before
 ifelse breed = cops [
   ;; move to a patch in vision; candidate patches are
   ;; empty or contain only jailed agents
   let targets neighborhood with
          [not any? cops-here and all? agents-here [jail-term > 0]]
   if any? targets [ move-to one-of targets ]
 ;; for agents: this has been changed
  ;; this introduces an asymmetry that provides an additional advantage for agents
 [if movement? [
   ;; move to a patch in vision
   ;; candidate patches are empty or contain only jailed agents and
   ;; they choose among them those with highest number of active agents around
   let targets neighborhood with
          [not any? cops-here and all? agents-here [jail-term > 0]]
   if any? targets [
   move-to max-one-of targets [count (agents-on neighborhood) with [active?]]
```

```
;; AGENT BEHAVIOR
to determine-behavior
set active? (grievance - risk-aversion * estimated-arrest-probability > threshold)
to-report grievance
 report perceived-hardship * (1 - government-legitimacy)
to-report estimated-arrest-probability
 let C count cops-on neighborhood
let A 1 + count (agents-on neighborhood) with [active?]
 ;; See Information tab for a discussion of the following formula
report 1 - \exp(-k * floor(C/A))
end
;; COP BEHAVIOR
to enforce
 if any? (agents-on neighborhood) with [active?] [
  ;; arrest suspect
  let suspect one-of (agents-on neighborhood) with [active?]
  ask suspect [
   set active? false
   set jail-term random max-jail-term
  move-to suspect ;; move to patch of the jailed agent
end
;; VISUALIZATION OF AGENTS AND COPS
to display-agent ;; agent procedure
ifelse visualization = "2D"
  [display-agent-2D]
  [ display-agent-3D ]
end
to display-agent-2D ;; agent procedure
 set shape "circle"
 ifelse active?
  [ set color red ]
  [ ifelse jail-term > 0
    [ set color black + 3 ]
    [ set color scale-color green grievance 1.5 -0.5 ] ]
end
to display-agent-3D ;; agent procedure
 set color scale-color green grievance 1.5 -0.5
 ifelse active?
  [ set shape "person active" ]
  [ ifelse jail-term > 0
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[ set shape "person jailed" ]
    [ set shape "person quiet" ] ]
end
to display-cop
 set color cyan
 ifelse visualization = "2D"
  [ set shape "triangle" ]
  [ set shape "person soldier" ]
end
;; PLOTTING
to update-plots
 let active-count count agents with [active?]
 let jailed-count count agents with [jail-term > 0]
 set-current-plot "Active agents"
 plot active-count
 set-current-plot "All agent types"
 set-current-plot-pen "active"
 plot active-count
 set-current-plot-pen "jailed"
 plot jailed-count
 set-current-plot-pen "quiet"
 plot count agents - active-count - jailed-count
end
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;; This model was created as part of the projects:
;; PARTICIPATORY SIMULATIONS: NETWORK-BASED DESIGN FOR SYSTEMS LEARNING IN
CLASSROOMS and/or INTEGRATED SIMULATION AND MODELING ENVIRONMENT.
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